# **CnC 5Axis Manufacturing of Gears**

using

# HyGEARS TM V 4.0

# An Overview

Involute Simulation Softwares Inc., Québec, Canada

October 2014



Introduction	3
Vector Simulation	4
HyGEARS : The Vector Model	5
Face Milling and Face Hobbing	7
Calibration	8
Supported Gear Types	12
5Axis CnC Post-Processor	
Overview	13
Main Features	14
Conversion	15
Machines	16
Tools	17
Display	20
Cycles	22
Metrics	32
Stock	33
Operations	34
Output	36
Sample results	40
Summary	44

### Introduction

Since its introduction in 1994, HyGEARS has been in constant evolution.

HyGEARS V 4.0 now covers all major gear types found in the gear industry. Its vector simulation model has been extensively tested and confirmed over the years.

And, notably, a **5Axis CnC Post-Processor** generates, from the **exact tooth definition** without any interpolation, the part programs to manufacture **every gear type** of the simulation model on **any 5Axis CnC machine** available on the market.

In one single stand alone software, HyGEARS allows users:

- to design gear sets: spiral-bevel, hypoid, straight bevel, Coniflex ™, spur, helical, Beveloid, herringbone, Face;
- to analyze the kinematics, unloaded and loaded: TE, Contact Pattern, FFT, Bending and Contact stresses, and more, are all but one click away;
- to enhance the kinematic characteristics of gear pairs, through specialized functions, in order to improve load carrying capacity and smoothness of operation;
- to assess the manufacturing quality through an export/import interface to common CMMs;
- to manufacture on conventional and 5 Axis CnC machines using Face Mill, Conical Side Milling Tool (or CoSIMT, such as made by Ingersoll Rand, Sandvik, PTR-TEC), End Mill and Ball Mill tools;
- the use of an **integrated Closed Loop**, i.e. the seamless use of CMM output to determine machine corrections such that manufactured parts are within set tolerances when compared to the design.

Read on for a brief overview of HyGEARS.

### HyGEARS is built on Vector Simulation



### **HyGEARS** The Vector Model

The coordinates and normal vectors at any point on the tooth flanks are obtained by applying machine specific rotations and translations to the cutter definition.

#### Point on tooth flank:

 $D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos(\alpha c) \sin(\alpha c) \\ 0 & -\sin(\alpha c) \cos(\alpha c) \end{bmatrix} \begin{bmatrix} S\cos(\phi) \\ 0 \\ (R \pm S\sin(\phi)) \end{bmatrix}$ 

 $X = \pmb{D} \ [\tau]^3 \ [k]^1 \ [Radial] \ [L_1]^3 [Dist] \ [\gamma_m]^2 [\theta_3]^3$ 

#### Normal on tooth flank:

$$N = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos(\alpha c) \sin(\alpha c) \\ 0 & -\sin(\alpha c) \cos(\alpha c) \end{bmatrix} \begin{bmatrix} \sin(\phi) \\ 0 \\ \mp \cos(\phi) \end{bmatrix}$$

 $N_x = N \, [\tau]^3 \, [k]^1 \, [L_1]^3 \, [\gamma_m]^2 [\theta_3]^3$ 



#### **HyGEARS** The Vector Model

Higher order changes can be superimposed to the tool and work piece movements in order to achieve specific kinematic behavior.

Example 1) Modified Roll higher order change:

$$L_{1m} = \alpha_3 R_r + \frac{2C}{2} (C_r - \alpha_3 R_r)^2 - \frac{6D}{6} (C_r - \alpha_3 R_r)^3 + \frac{24E}{24} (C_r - \alpha_3 R_r)^4 - \frac{120F}{120} (C_r - \alpha_3 R_r)^5 + \frac{720G}{720} (C_r - \alpha_3 R_r)^6$$

#### Example 2) Helical Motion higher order change:

$X_{bm} = X_b + 1_{st} (C_r - \alpha_3 R_r)^{\Box} + 2_{nd} (C_r - \alpha_3 R_r)^2 + 3_{rd} (C_r - \alpha_3 R_r)^2 + 3_$
$(\alpha_3 R_r)^3 + 4_{th} (C_r - \alpha_3 R_r)^4 + 5_{th} (C_r - \alpha_3 R_r)^5 + 6_{th} (C_r - \alpha_3 R_r)^6$

where:	$L_{1m}$ :	modified cradle angle	where:	X <sub>bm</sub> :	modified sliding base
	α <sub>3</sub> :	work piece roll angle		α <sub>3</sub> :	work piece roll angle
	R <sub>r</sub> :	ratio of roll, cradle to work piece		R <sub>r</sub> :	ratio of roll, cradle to work piece
	C <sub>r</sub> :	cradle ref. position		C <sub>r</sub> :	cradle ref. position
				$1^{st}$ :	1 <sup>st</sup> Order parameter
	2C:	2 <sup>nd</sup> Order parameter (Gleason notation)		$2^{nd}$ :	2 <sup>nd</sup> Order parameter
	6D:	3 <sup>rd</sup> Order parameter		3 <sup>rd</sup> :	3 <sup>rd</sup> Order parameter
	24E:	4 <sup>th</sup> Order parameter		4 <sup>th</sup> :	4 <sup>th</sup> Order parameter
	120F:	5 <sup>th</sup> Order parameter		$5^{\text{th}}$ :	5 <sup>th</sup> Order parameter
	720G:	6 <sup>th</sup> Order parameter		6 <sup>th</sup> :	6 <sup>th</sup> Order parameter

### **<u>HyGEARS</u>** – Face Milling and Face Hobbing

Both the Face Milling and Face Hobbing processes are supported for Spiral Bevel gears.



Face Milling (single indexing)



Face Hobbing (continuous indexing)

### HyGEARS - Calibration

Over the years, HyGEARS has been extensively calibrated against Gleason's and Klingelnberg's TCA for Contact Pattern and Transmission Error, CMM output, Corrective Machine Settings (Closed Loop), LTCA Contact Stresses, etc.

Some important milestones:

1993-1994:	Machine Calibration (Gleason and Yutaka machines)
1994:	Closed Loop 1 <sup>st</sup> Order
1995:	Closed Loop 2 <sup>nd</sup> Order
1996:	Experimental TE
1997:	Experimental LTCA
1998:	Fillet Stress (against FEA)
2001:	Contact Stress (against Gleason)
2004:	Bending and Contact Stress – Face Hobbing – (against Gleason)
2006:	Lapping Prediction (with AAM)

Consistently equivalent results are obtained, as is shown in the following pages.



#### HyGEARS - Calibration

8x39 Face Milled Spiral Bevel gear set: HyGEARS vs Gleason and KIMoS Nominals



### HyGEARS - Calibration

#### 8x39 Face Hobbed Hypoid gear set: HyGEARS vs Gleason and KIMoS Nominals



### HyGEARS - Supported Gear Types

The most popular gear types are supported by HyGEARS. All can be cut on any 5Axis CnC machines !

- Spur/Helical
- Herringbone
- Spiral Bevel, Face Milled and Face Hobbed
- Hypoids, both conventional and High Ratio (HRH)
- Straight Bevels
- Coniflex (TM The Gleason Works)
- Beveloid
- Face Gears
- Spiral Face Clutches



#### Overview:

HyGEARS integrates a **5Axis Post-Processor** that can generate CnC part programs to cut **any HyGEARS** supported gear type on any 5 Axis CnC machine.

The part programs, based on the exact tooth definition, **need no further intervention** and can be uploaded directly to any 5Axis CnC machine.

**Tool and machine movements are displayed in 3D**, can be rotated in any direction for better viewing, and can be animated or single stepped to allow visualization and collision detection throughout the tool path.

The use of the Post-processor is easy, intuitive, and reflects the actual work done on the shop floor.

The Post-processor supports machine architectures of "BA", "BC", "AB" and "AC" types, where :

- the A axis rotates about the X axis
- the B axis rotates about the Y axis
- the C axis rotates about the Z axis

Specific machines with special kinematics can be created and saved for later use: the translation and rotation axes can be renamed, and their positive direction can be inverted.

*Typical tools include Face Milling, Coniflex*<sup>TM</sup> *dish, CoSIMT (i.e. Conical Side Milling Tool), End Mill and Ball Mill cutters. A tool box for each tool type can be created by the users to suit their needs.* 

#### Main features of the Post-Processor:

- *supports "AB", "AC", "BA" and "BC" architecture machines;*
- supports GCodes, Heidenhain, Siemens and Fanuc controllers;
- supports Traori (Siemens), TCPM (Heidenhain) and TCP (Fanuc);
- allows creation of specific 5Axis machines from the 4 basic architectures; specific machines can be fully customized by the user to reproduce exactly the machine implementation;
- offers 10 pre-defined cutting cycles for CoSIMT, End Mill and Ball Mill tools; and 4 pre-defined cutting cycles for Face Mill tools (single roll/double roll);
- CoSIMT cutting edges can be linear or circular (to cut a Face Gear for example);
- allows single pass roughing / multi-pass semi-finishing and finishing for CoSIMT, End Mill and Ball Mill tools;
- allows the generation of a protuberance in the fillet;
- the tool path is easily customized by the user in order to optimize both cycle time and product quality;
- allows automated / single stepping animation of the tool and work piece through the cutting cycle;
- allows the display of the supporting arbor and the machine head to detect potential collisions;
- allows the creation of "Operations" which define a given task; Operations can be re-used on different gears;
- allows the creation of "Processes" which are a series of "Operations" in a given order; Processes can thus generate a complete single file part program including roughing and semi-finishing of the tooth flank and fillet using different tools.

#### Part Programs:

- *can be in CSV (comma separated values) format for import in Excel;*
- can include or exclude comments describing the operations performed;
- can be for Face Milling cutters (spiral bevel gears), Dish type cutters (Coniflex ™ The Gleason Works gears), CoSIMT (such as made by Ingersoll Rand, Sandvik, PTR-TEC), End Mill, Ball Mill cutters.

**Conversion:** To generate a part program, HyGEARS converts the movements of the conventional cutter in a conventional machine into movements of a Face Mill, Coniflex<sup>™</sup> dish, CoSIMT, End Mill or a Ball Mill tool in a 5Axis CnC machine where:

- the relative position and orientation between the ref. frames of the CnC machine tool and the conventional cutter are maintained.
- the relative position and orientation of the ref. frames of the conventional cutter and the work piece are maintained.

The figure to the right shows a Face Mill cutter (pink) and a CoSIMT (green) with coincident cutting edges.

The HyGEARS Post Processor tracks the movements of the Face Mill cutter in the conventional machine and converts them to CoSIMT movements in a 5Axis CnC machine.

The same approach is applied to all tools and gear types.



Machines: 4 basic machines are available: BC, AC, AB and BA (bottom left figure).

Any specific machine can be derived from the basic types using the HyGEARS machine editor (bottom right figure).



Tools: HyGEARS offers 5 different tools:	Face Mill cutter	(for spiral bevel gears)
	Dish cutter	(for Coniflex <sup>TM</sup> gears)
	CoSIMT	(for all gear types)
	End Mill	(for all gear types)
	Ball Mill	(for all gear types)



*Tools:* Each tool type is described in a dedicated data page where the defining dimensions are entered by the user. The 30 character-long tool name is user defined.

The tools can be saved for re-use and are specific to users, i.e. they are not distributed with HyGEARS. Hence, proprietary information remains proprietary.

End Mill Details	Name:	8mm Bull Nose 8mm Bull Nose  Clear Save Delete 1/16taperball
Diameter Edge radius	8.0000 2.0000	2mm Bull Nose 3mm Bull Nose 4mm Breton 7mm+taper-ball
Cone Angle Cutting Length	0.0000	Stem Diameter Stem Diameter DS 06/18
Cutting Length in Use	44.9999	DS 08/26
Tool Length	80.0001	DS 10/32 Length
	0.0000	Cone Angle DS 12/40 - 40degAngle DS 12/40 -
Fillet Rad. [Toe]	1.5467	Kugettraser D6
Fillet Rad. [Heel]	1.4659	
Slot Width [Toe]	4.2845	Feeds [mm/min]
Slot Width [Heel]	4.1220	Rapid move 1500.0 Plunge 50.0 Cutting 500.0
		Qutput Apply +/- Anim QK Cance

**Tools:** CoSIMT tools can have circular cutting edges which allow the generation of tooth profiles with concave curvature, such as Face Gears.



Definition of a CoSIMT

**Display:** Several options allow selective information display. These include:

- the Tool Holder,
- the Work Arbor and support,
- the Target Grid, where the target coordinates are displayed in wire frame mesh,
- *the Target Volume which will be removed by the selected operation.*

a <sup>w</sup> 5 Axis CnC - Pinion 22x35-DH-454.HyG	i - [mm]	" Cutting Machine
Machine/Tool Cutting Cycle Metrics Arb	or End Mill Op/Process Stock	Cutting Machine CnC [Universal 5 Axis 'A-C'] Pinion [Finishing][Nominal]- ConvexIB
Machine Selection	Cutting Tool	
Universal 5 Axis CnC "B-C"	Face Mill Cutter 📝 Hide cutter body	
Ouriversal 5 Axis CnC "A-C"	Invert Work 🗸 Outside Blade	
<ul> <li>Universal 5 Axis CnC "A-B"</li> <li>Universal 5 Axis CnC "B-A"</li> </ul>	Invert Arbor V Inside Blade	
	i ind Mill	
CT-8000	Ball Mill	
New Edit Delete	Roughing	
Compensation	Misceleanneous	
Tool Center Point	Apex Location 0.000	
Absolute	Display Tool Holder	
Differential	Display Arbor	
	✓ Display Target Grid	80.792
	✓ Display Target Volume	
		x x
Qư	tput Apply +/- Anim OK Cancel	[[q: 5.7/R: 10.62/X: 24.4828/Y: 70.2927/Z: -0.6520/A: -59.2607/C: 199.1074]
		Display of the Target Grid (beige) and Volume (light blue)

Display: example of Tool Holder and Work Arbor with CoSIMT and 1.2 mm module hypoid pinion.



*Cycles: Cutting cycles can be extensively tailored to user preferences, depending on tool choice.* 

💅 5 Axis CnC - Pinion 6x60.hyg - [mm]							
Machine/Tool Cutting Cycle Metrics Arbor End Mill Op/Process Stock							
Output Format Stock/Feed Read Sting Actual							
CSV Format	# Steps	50 [5	50] — Start: 1 📄 Display				
CMM Coords/ Normals	# Facewidth Pts	11	End: 50 🔲 Display				
No comment lines	Retract Factor	2.0					
Coordinates only	Finish Stock	0.000					
Work coordinates	Rough Stock	0.127					
TCP (Fanuc)	Constant D-Radiu	is 🔽 Me	oving Contact Pnt 📃				
	Clearance		Indexing Sequence				
Tooth Toe 0.0 Skip # 1							
Cutting Cycle	ID Cide		OR Cide				
Slot By Slot		Tee					
Flank by Flank	Heel -> Toe ->	> Heel	Heel -> Toe -> Heel				
Fillet / Root	Toe -> Heel	211001	Toe -> Heel				
Tooth Flank	Heel -> Toe		Heel -> Toe				
<ul> <li>Tip Deburning Tool Side</li> <li>Tip Deburning Tool End</li> </ul>	IB-OB O-Shap	bed	OB-IB O-Shaped				
Depth 0.000	🔘 Rock Me (ba	be)					
Qutput Apply +/- Anim QK Cancel							

Cycle Options for CoSIMT, End Mill and Ball Mill tools

- Stock feed along the face width (#Facewidth Pts) and tooth depth (#Steps)
- When cutting starts and ends (Start / End)
- Tool retraction at end of cycle (Retract Factor)
- Whether the tooth description is with constant roll angles or radius (Constant D-Radius)
- Whether the contact point moves or not along the cutting edge (Moving Contact Pnt)
- Toe and Heel clearances
- Indexing sequence in order to spread tool wear and thermal load over non sequential teeth (Skip#).

*Cycles:* HyGEARS offers up to 10 different cutting cycles for CoSIMT, End Mill and Ball Mill tools, 4 cycles for Face Mill cutters and 1 cycle for the Coniflex<sup>™</sup> dish cutter.

🛫 5 Axis CnC - Pinion 6x60.hyg - [mm]	😴 5 Axis CnC - Pinion 6x60.hyg - [mm]
Machine/Tool Cutting Cycle Metrics Arbor Face Mill Op/Process Stock	Machine/Tool Cutting Cycle Metrics Arbor End Mill Op/Process Stock
Output Format Stock/Feed	Output Format Stock/Feed Reqd. Sugg. Actual
CSV Format # Steps 50	CSV Format # Steps 50 [50] — Start: 1 Display
CMM Coords/ Normals # Facewidth Pts 11	CMM Coords/ Normals # Facewidth Pts 11 End: 50 Display
No comment lines Retract Factor 2.0	No comment lines Retract Factor 2.0
Coordinates only Finish Stock 0.000	Coordinates only Finish Stock 0.000
Work coordinates Rough Stock 0.127	Work coordinates Rough Stock 0.127
TCP (Fanuc) Constant D-Radius V Moving Contact Pnt	TCP (Fanuc) Constant D-Radius V Moving Contact Pnt
Clearance     Indexing Sequence       Tooth Toe     0.0       Skip # 1       Tooth Heel     0.0	Clearance     Indexing Sequence       Tooth Toe     0.0       Skip # 1       Tooth Heel     0.0
Cutting Cycle         Roll Cycle         Image: Single Roll - Toe to Heel         Single Roll - Heel to Toe         Double Roll - Toe to Heel         Double Roll - Heel to Toe	Cutting Cycle       IB Side       OB Side         Image: Slot By Slot       Toe -> Heel -> Toe       Toe -> Heel -> Toe         Fillet / Root       Toe -> Heel       Toe -> Heel         Top Tip Deburing Tool Side       The Heel -> Toe       Heel -> Toe         Tip Deburing Tool Side       IB-OB O-Shaped       OB Side         Depth       0.000       Rock Me (babe)       OB Side

Cycles for Face Mill cutters

Cycles for CoSIMT, End Mill and Ball Mill tools

#### Cycles: CoSIMT, End Mill and Ball Mill tools.

Stock/Feed       Reqd.       Sugg.       Actual         CSV Format       # Steps       50       [50]       Statt: 1       Display         CMM Coords/ Nomals       # Steps       50       [50]       Statt: 1       Display         No comment lines       Facewidth Pts       11       End: 50       Display         Coordinates only       Retract Factor       2.0       Finish Stock       0.000         Work coordinates       Constant D-Radius       Moving Contact Pnt       Indexing Sequence         TCP (Fanuc)       Cost Toe       0.0       Toe       Skip # 1         Tooth Toe       0.0       Mirror       Mirror       Skip # 1         Tooth Heel       0.0       Mirror       Mirror       Skip # 1         Tooth Toe       0.0       Mirror       Mirror       Skip # 1         Tooth Toe       0.0       Mirror       Mirror       Skip # 1         Tooth Teel       Toe -> Heel       Toe -> Heel       Toe -> Heel <th colspan="8">Machine/Tool Cutting Cycle Metrics Arbor End Mill Op/Process Stock</th>	Machine/Tool Cutting Cycle Metrics Arbor End Mill Op/Process Stock								
CSV Format       # Steps       50       50       Start: 1       Display         CMM Coords / Nomals       # Facewidth Pts       11       End: 50       Display         No comment lines       Retract Factor       2.0       Finish Stock       0.000         Work coordinates       Finish Stock       0.000       Rough Stock       0.127         TCP (Fanuc)       Clearance       Indexing Sequence         Cutting Cycle       Is Side       Other Stock       O.0         Stot By Slot       Fallet / Root       Toe -> Heel -> Toe       Heel -> Toe         Fillet / Root       Top Deburning Tool Side       Heel -> Toe       OB Side         Tip Deburning Tool End       Depth       0.00       OB Shaped         Optimut       Apply       t/a       Apply       0/a	Output Format Stock/Feed Read Stude Actual								
CMM Coords/ Nomals       # Facewidth Pts       11       End:       50       Display         No comment lines       Retract Factor       2.0       Retract Factor       2.0         Coordinates only       Work coordinates       0.000       Rough Stock       0.127         TCP (Fanuc)       Constant D-Radius       Moving Contact Pnt       Indexing Sequence         Cotting Cycle       Is Side       0.0       Ninror         Cutting Cycle       IB Side       OB Side       Indexing Sequence         Fillet / Root       Toe -> Heel       Toe -> Heel       Index = > Toe         Fillet / Root       Toe -> Heel       Toe -> Heel       Toe -> Heel         Tip Deburning Tool Side       IB-OB O-Shaped       OB-IB O-Shaped         Depth       0.000       Rock Me (pabe)       OK	CSV Format	# Steps	50 [	[50] - Start: 1 Display					
No comment lines       Retract Factor       2.0         Coordinates only       Work coordinates       0.000         Work coordinates       0.127         TCP (Fanuc)       Constant D-Radius       Moving Contact Pnt         Clearance       Indexing Sequence         Tooth Toe       0.0       Mirror         Cutting Cycle       Is Side       Toe -> Heel         Fillet / Root       Toe -> Heel       Heel -> Toe         Tip Deburing Tool Side       IB-OB O-Shaped       OB-IB O-Shaped         Tip Deburing Tool End       Rock Me (pabe)       OB-IB O-Shaped	CMM Coords/ Normals	# Facewidth Pts	11	End: 50 Display					
□       Coordinates only         □       Work coordinates         □       TCP (Fanuc)         □       Cearance         □       Indexing Sequence         □       Tooth Toe       0.0         □       Tooth Toe       0.0         □       Tooth Toe       0.0         □       Tooth Toe       0.0         □       Tooth Tee       0.0         □       Tooth Tee       0.0         □       Tooth Tee       0.0         □       Tooth Tee       0.0         □       Tooth Heel       0.0         □       Too -> Heel -> Toe       Heel -> Toe         □       Tip Debuming Tool Side       □         □       Tip Debuming Tool End       □         □       Tip Debuming Tool End       □         □       Tooth Rek       □         □       Tip Debuming Tool End       □         □       Tooth Rek       □         □       Tooth Rek       □         □       Tip Debuming Tool End       □         □       Tooth Rek       □         □       Tooth Rek       □         □       Othet	No comment lines	Retract Factor	2.0						
Work coordinates       Rough Stock       0.127         TCP (Fanuc)       Constant D-Radius       Moving Contact Pnt         Clearance       Indexing Sequence         Tooth Toe       0.0         Skip # 1       Tooth Toe         Tooth Toe       0.0         Bilde       Skip # 1         Tooth Heel       U.U         Mirror       Mirror         Cutting Cycle       IB Side         Stot By Slot       Toe -> Heel -> Toe         Rank by Flank       Toe -> Heel -> Toe         Fillet / Root       Toe -> Heel         Tooth Flank       Toe -> Heel         Tip Deburning Tool Side       IB-OB O-Shaped         Depth       0.00	Coordinates only	Finish Stock	0.000						
Constant D-Radius       ✓ Moving Contact Pnt         Clearance       Indexing Sequence         Tooth Toe       0.0         Nimor       Skip # 1         Tooth Heel       0.0         Mirror       Mirror         Cutting Cycle       IB Side         Image: Slot By Slot       IB Side         Flank by Flank       Image: Slot By Slot         Fillet / Root       Toe -> Heel         Tooth Flank       Toe -> Heel         Tip Debuming Tool Side       IB-OB O-Shaped         Depth       0.00	Work coordinates	Rough Stock	0.127						
Clearance Tooth Toe       Indexing Sequence Skip # 1         Tooth Toe       0.0         Nimor       Skip # 1         Tooth Heel       0.0         Minor       Minor         Cutting Cycle       IB Side         Slot By Slot       Toe -> Heel -> Toe         Fillet / Root       Toe -> Heel         Top Deburing Tool Side       Heel -> Toe         Tip Deburing Tool Side       IB-OB O-Shaped         Depth       0.00	TCP (Fanuc)	Constant D-Radiu	us 🔽 N	loving Contact Pnt 📃					
Tooth Toe       0.0       Skip # 1         Tooth Heel       0.0       Mirror         Cutting Cycle       IB Side       Mirror         Image: Slot By Slot       Image: Slot By Slot       Image: Slot By Slot         Image: Fillet / Root       Toe -> Heel -> Toe       Image: Slot By Slot         Image: Fillet / Root       Toe -> Heel       Image: Slot By Slot         Image: Fillet / Root       Toe -> Heel       Image: Slot By Slot         Image: Fillet / Root       Toe -> Heel       Image: Slot By Slot         Image: Fillet / Root       Toe -> Heel       Image: Slot By Slot         Image: Fillet / Root       Toe -> Heel       Image: Slot By Slot         Image: Fillet / Root       Toe -> Heel       Image: Slot By Slot         Image: Fillet / Root       Toe -> Heel       Image: Slot By Slot         Image: Fillet / Root       Image: Slot By Slot       Image: Slot By Slot By Slot         Image: Fillet / Root       Toe -> Heel       Image: Slot By		Clearance		Indexing Sequence					
Tooth Heel       0.0       Mirror         Cutting Cycle       IB Side       OB Side         Image: Slot By Slot       Image: Slot By Slot       Image: Slot By Slot       OB Side         Flank by Flank       Image: Slot By Slot       Image: Slot By Slot       OB Side         Flank by Flank       Image: Slot By Slot       Image: Slot By Slot       Image: Slot By Slot       OB Side         Flank by Flank       Image: Slot By Slot       Image: Slot By Slot       Image: Slot By Slot       OB Side         Fillet / Root       Image: Slot By Slot       Image: Slot By Slot       Image: Slot By Slot       OB Side       Image: Slot By Slot         Fillet / Root       Too -> Heel       Too -> Heel       Image: Slot By Slot       Image: Slot By Slot By Slot By Slot       Image: Slot By Slot	Tooth Toe 0.0 Skip # 1								
Cutting Cycle       IB Side       OB Side <ul> <li>             Flank by Flank         </li> <li>             Fillet / Root             <li>             Toe -&gt; Heel         </li> <li>             Deburning Tool End         </li> <li>             Depth 0.000         </li> </li></ul> <ul> <li>             Detart Apply         </li> </ul> <ul> <li>             Depth 0.000         </li> </ul>	Tooth Heel 0.0 Mirror								
Slot By Slot   Fank by Flank   Fillet / Root   Tooth Flank   Tip Deburning Tool Side   Tip Deburning Tool End   Depth   0.000    Output	Cutting Cycle								
Image: Second state sta	Slot By Slot	IB Side		OB Side					
Image: State of the state	<ul> <li>Flank by Flank</li> </ul>	Toe -> Heel	> Toe	Toe -> Heel -> Toe					
Image: Provide the second state in		Heel -> Toe -	> Heel	Heel -> Toe -> Heel					
○ Tip Deburning Tool Side     ○ Heel -> Toe     ○ Heel -> Toe       ○ Tip Deburning Tool End     ○ IB-OB O-Shaped     ○ OB-IB O-Shaped       ○ Depth     0.000     ○ Rock Me (babe)	Tooth Flank	Toe -> Heel		Toe -> Heel					
Tip Deburning Tool End     IB-OB O-Shaped     OB-IB O-Shaped       Depth     0.000     Rock Me (babe)     OB-IB O-Shaped	Tip Deburring Tool Side	Heel -> Toe	Heel -> Toe						
Depth 0.000 O Rock Me (babe)	Tip Deburring Tool End	IB-OB O-Shaped     IB-OB O-Shaped							
	Depth 0.000	Rock Me (ba	be)						
	Output Apply +/- Anim OK Cancel								

Cycles for CoSIMT, End Mill and Ball Mill tools

- Fillet, Tooth Flank and Tip Deburring/Chamfering are different operations;
- They can be cut Slot by Slot or Flank by Flank, depending on machine selection, work size, and how much travel is required by the machine or tool between tooth flanks;
- Cutting cycles need not be the same on both tooth flanks;

#### Cycles: Face Mill Cutter

🕈 5 Axis CnC - Pinion 6x60.hyg - [mm]						
Machine/Tool Cutting Cycle Metr	ics Arbor Face Mill Op/Process Stock					
Output Format	Stock/Feed					
CSV Format	# Steps 50					
CMM Coords/ Normals	# Facewidth Pts 11					
No comment lines	Retract Factor 2.0					
Coordinates only	Finish Stock 0.000					
Work coordinates	Rough Stock 0.127					
TCP (Fanuc)	Constant D-Radius IV Moving Contact Pnt					
	Clearance Indexing Sequence					
Tooth Toe 10.0 Skip # 1						
Tooth Heel 10.0 Mirror						
Cutting Cycle						
Roll Cycle						
Single Roll - Toe to Heel						
Single Roll - Heel to Toe						
Double Roll - Heel to Toe						
	Output Apply +/- Anim OK	Cancel				

Cycles for Face Mill cutters

- *can be Single Roll/Double Roll;*
- Double Roll plunges the cutter to full depth between the start and end of the 1<sup>st</sup> roll, and then generates full depth on the 2<sup>nd</sup> roll;
- can be Toe to Heel or Heel to Toe;
- the use of Toe/Heel clearances allows progressive cutter entry/retract for better tool life (see the Target Volume in light blue below);
- the Indexing Sequence allows spreading tool wear and thermal load over non-consecutive tooth slots.



#### Cycles: Face Mill Cutter

<sup>217</sup> 5 Axis CnC - Pinion Machine/Tool Cutting	6x60.hyg - [m Cycle   Metrics	nm] s Arbor Fac	ce Mill Op/F	Process Stock	
Face Mill Details	Name:	58 mm Body Clear Sa	ve Delete	58 mm Bod	y <b>-</b>
Body Diameter Body Height Blade Depth Number of Blades	58.0000 3.2674 3.2674 12		Bod	y Diameter	Body Height
					Blade Depth
		Feeds Rapid r	<b>(mm/min)</b> nove 1500	Plunge 50	Cutting 500
		Qutput	Apply	+/- <u>A</u> ni	m <u>O</u> K <u>C</u> ancel

- the Face Mill cutter used on the 5Axis CnC machine can be defined and saved;
- *cutter Diameter, Blade angles, Edge Radii, and Point Width are those described in the Summary Editor (see below).*

Pinic	on (Hypo	id] [Finishi	ng][Nomi	nal] 6x60.	hyg - [m	nm] [dd.mn	n.ss]	×
Blank	Cutter	TopRem	Machine	Hi Order	Other	Operating	Rim/Material	Bea 🔸 🕨
Cut	ter Units						🔘 [in] 🛛 🧕	) [mm]
				Conca	ave-OB		Convex-IB	
Ave	erage Diar	meter		50.9	146			
Bla	de Angle			17.3	000		22.4000	
B.E	dge Rad.			0.20	00		0.2000	
Poir	nt Width			0.45	50			
Cut	ter Edge			Strai	ght	-	Straight	-
Rad	d. of Curva	ature		0.00	00		0.0000	
Ref	. Height			0.53	50		0.5350	
Nur	nber of Bl	ades		20		_		
	ter Gaging	]		0.00	00			
						Apply	у <u>о</u> к	Cancel

Face Mill cutter definition

#### Cycles: CoSIMT, End Mill, Ball Mill

🕷 5 Axis CnC - Pinion 6x60.hyg -	[mm]					x
Machine/Tool Cutting Cycle Metri	cs Arbor CoS	IMT Op/Pr	ocess S	tock		
Output Format	Stock/Feed	Regd.	Sugg.	ł	Actual	
CSV Format	# Steps	11	[11]	- Start:	1 Display	r
CMM Coords/ Normals	# Facewidth	Pts 11		End:	11 🔲 Display	r
No comment lines	Retract Fact	or 2.0				
Coordinates only	Finish Stock	0.000				
Work coordinates	Rough Stock	0.127	]			
TCP (Fanuc)	Constant D-Radius 🛛 Moving Contact Pnt 📃			Pnt		
	Clearance		In	ndexing S	Sequence	
	Tooth Toe	10.0		Skip #	1	
	Tooth Heel	10.0		Mirror		1
Cutting Cycle						
Slot By Slot	IB Side			B Side		
Flank by Flank	Toe -> H	leel -> Toe	(	Toe ->	Heel -> Toe	
C Fillet / Root	⊘ Heel ->	Toe -> Heel	0	) Heel ->	Toe -> Heel	
<ul> <li>Tooth Flank</li> </ul>	○ loe -> l	leel	0	) loe->	Heel	
Tip Deburning Tool Side	⊘ Heel ->	loe	0	) Heel ->	Toe	
Tip Deburning Tool End	IB-OB 0	-Shaped	(	○ OB-IB C	D-Shaped	
Depth 0.000	Rock M	e (babe)				
	Output	Apply	+/-	<u>A</u> nim	OK Cano	;el

Cycles for CoSIMT, End Mill and Ball Mill tools

- CoSIMT can rough tooth flanks and fillet;
- CoSIMT, End Mill and Ball Mill can finish tooth flanks;
- Bull Nose End Mill and Ball Mill can finish the fillet, and a protuberance can be imposed in the form of negative Stock;
- End Mill can Deburr / Chamfer tooth Tip;
- *Positive and Negative stock can be used.*



#### Cycles: End Mill: Toe-Heel-Toe (IB-Side) / Heel-Toe-Heel (OB-Side)

Machine/Tool Cutting Cycle Met	trics Arbor End Mill Op/Prod	cess Stock
Output Format CSV Format CMM Coords/ Normals No comment lines Coordinates only Work coordinates	Stock/Feed # Steps 7 # Facewidth Pts 11 Retract Factor 2.0 Finish Stock 0.000 Rough Stock 0.127 Constant D.Badius	Sugg. Actual [5] Start: 1 Display End: 5 Display
	Clearance Tooth Toe 0 Tooth Heel 0	Indexing Sequence Skip # 1 Mirror
Slot By Slot     Filet / Root     Tooth Flank     Tip Deburring Tool Side     Tip Deburring Tool End     Depth 0.000	IB Side Toe -> Heel -> Toe Heel -> Toe -> Heel Toe -> Heel Heel -> Toe IB-OB O-Shaped Rock Me (babe)	OB Side Toe -> Heel -> Toe Heel -> Toe -> Heel Toe -> Heel Heel -> Toe OB-IB O-Shaped
	Qutput Apply +	-/- <u>A</u> nim <u>O</u> K <u>C</u> ance

- Cutting cycles can be different for each tooth flank (IB-OB, Left-Right);
- a cutting cycle starts on the IB and finishes on the OB (Left-Right flanks for non spiral-bevels);
- for example, with the selections made in the left figure, given the IB cycle ends at Heel, unless otherwise dictated it would make sense to start the OB cycle at Heel to save cycle time (the tool path is the red line in the figure below).



#### Cycles: IB-OB O-Shaped / OB-IB O-Shaped

🚏 5 Axis CnC - Pinion 6x60.hyg -	[mm]		<b>—</b> X
Machine/Tool Cutting Cycle Metr	ics Arbor End Mill	Op/Process	Stock
Output Format	Stock/Feed	Regd. Sug	gg. Actual
CSV Format	# Steps	7 [5	5] — Start: 1 📃 Display
CMM Coords/ Normals	# Facewidth Pts	11	End: 5 📃 Display
No comment lines	Retract Factor	2.0	
Coordinates only	Finish Stock	0.000	
Work coordinates	Rough Stock	0.127	
TCP (Fanuc)	Constant D-Rad	ius 🔽 Mo	oving Contact Pnt 📃
	Clearance Tooth Toe Tooth Heel	0	Indexing Sequence Skip # 1 Mirror
Cutting Cycle  Slot By Slot Rank by Rank Fillet / Root	IB Side Toe -> Heel Heel -> Toe	-> Toe -> Heel	OB Side Toe -> Heel -> Toe Heel -> Toe -> Heel Toe -> Heel
Tooth Flank	Toe -> Heel		Heel > Toe
<ul> <li>Tip Deburring Tool Side</li> <li>Tip Deburring Tool Field</li> </ul>	IB-OB O-Sh	aped	OB-IB O-Shaped
Depth 0.000	<ul> <li>Rock Me (b)</li> </ul>	abe)	
	Output App	ly +/-	<u>A</u> nim <u>O</u> K <u>C</u> ancel

- only one starting flank can be selected, the other being slave;
- for IB-OB, the cutting cycle takes a pass along the face width on the IB and switches to the OB for return; the cycle then switches back to the IB and takes one step depth wise before starting over again;
- can be a real time saver when used with a Tapered End Mill or a CoSIMT.



IB-OB O-Shaped cycle

Cycles: Rock-Me (Babe)

achine/Tool Cutting Cycle Me	trics Arbor CoSIMT Op	p/Process Stock
Output Format	Stock/Feed	ad. Sugg. Actual
CSV Format	# Steps 7	[7] - Start: 1 Display
CMM Coords/ Normals	# Facewidth Pts 4	End: 7 Display
No comment lines	Retract Factor 2.0	D
Coordinates only	Finish Stock 0.0	000
Work coordinates	Rough Stock 0.	127
TCP (Fanuc)	Constant D-Radius	Moving Contact Pnt
	Clearance	Indexing Sequence
	Tooth Toe 0	Skip # 1
	Tooth Heel 0	Mirror
Cutting Cycle		,
Slot By Slot	IB Side	OB Side
<ul> <li>Flank by Flank</li> </ul>	Toe -> Heel -> To	oe 💿 Toe -> Heel -> Toe
-	Heel -> Toe -> H	eel   Heel -> Toe -> Heel
Fillet / Root     Taath Baala	Toe -> Heel	Toe -> Heel
Tooth Flank Tip Deburring Tool Side	Heel -> Toe	Heel -> Toe
Tip Deburring Tool End	IB-OB O-Shaped	OB-IB O-Shaped
Depth 0.000	Rock Me (babe)	

Rock Me (babe) cycle

- the cycle starts at IB Toe-Tip, generates depth wise to the Fillet, switches to the OB and generates from Fillet to Tip, advances along the OB face width, generates depth wise along the OB side to the Fillet, switches to the IB and generates till Tip, advances along the IB face width, and starts over until Heel is reached;
- this process is well suited to CoSIMT and finishing in one operation.



Cycles: Fillet

Nachine/Tool Cutting Cycle Me	trics Arbor End Mill Op/Pro	ocess Stock
Output Format	Stock/Feed Regd.	Sugg. Actual
CSV Format	# Steps 6	[6] — Start: 1 📃 Display
CMM Coords/ Normals	# Facewidth Pts 17	End: 6 🔲 Display
No comment lines	Retract Factor 2.0	
Coordinates only	Finish Stock 0.000	
Work coordinates	Rough Stock 0.127	
TCP (Fanuc)	Constant D-Radius	Moving Contact Pnt
	Clearance	Indexing Sequence
	Tooth Toe 0	Skip # 1
	Tooth Heel 0	Mirror
Cutting Cycle		
Slot By Slot	IB Side	OB Side
Flank by Flank	Toe -> Heel -> Toe	Toe -> Heel -> Toe
Ellet / Past	Heel -> Toe -> Heel	Heel -> Toe -> Heel
<ul> <li>Tooth Flank</li> </ul>	Toe -> Heel	Toe -> Heel
Tip Deburring Tool Side	Heel -> Toe	Heel -> Toe
Tip Deburring Tool End	IB-OB O-Shaped	OB-IB O-Shaped
Depth 0.000	Rock Me (babe)	

- Fillet finishing is integral to tooth flank finishing when using a Face Mill or CoSIMT tool since the tool sweeping movement generates the fillet;
- Fillet finishing can be done in a distinct operation when using an End Mill or Ball Mill tool; in such conditions, negative Stock can be imposed to produce a protuberance;
- Fillet finishing uses the same cycles as for Flank finishing (except Rock Me (babe)).



Fillet cycles

Metrics: The Metrics page lists, step by step, what are the expected differences between:

- the continuous theoretical tooth profile, both depth wise and along the face width, and
- *the discrete tool paths whose envelope form the tooth flanks.*

It therefore helps the user select an optimal number of Steps Profile and Length wise to have a smooth finish and yet maintain cycle time to a minimum.

ping billion	sions				Stepping Dimensions		
		Fillet Wis	e			Length Wise	
Finishing	g Convex-IB	[Toe] [mm]			Finishing Convex-	IB [mm]	
Step#	Slot Width	Step Depth	Flat Width	Peak-Fill.	Point#	Flat Length	Flat-Fill.
[Tooth Fo	orm Diameterl				[Tee]		
1/6	0.5900	0.1916	0.0680	0.0034	1/17	1.1868	0.0191
2/6	0.5286	0.1670	0.0685	0.0035	2/17	1.1999	0.0194
3/6	0.4530	0.1430	0.0687	0.0035	3/17	1.2137	0.0197
4/6	0.3664	0.1197	0.0683	0.0036	4/17	1.2272	0.0199
5/6	0.2724	0.1522	0.1930	0.0217	5/17	1.2417	0.0202
6/6	0.0000	0.0000	0.000	0.0000	6/17	1.2566	0.0204
Total :		0.7735			7/17	1.2723	0.0207
					8/17	1.2884	0.0209
Finishing	g Convex-IB	[Heel] [mm]			9/17	1.3055	0.0212
Step#	Slot Width	Step Depth	Flat Width	Peak-Fill.	10/17	1.3234	0.0215
					11/17	1.3423	0.0218
[Tooth Fo	orm Diameter]				12/17	1.3624	0.0221
1/6	0.6065	0.3341	0.0754	0.0038	13/17	1.3836	0.0225
2/6	0.5409	0.2851	0.0776	0.0040	14/17	1.4063	0.0229
3/6	0.4616	0.2384	0.0790	0.0042	15/17	1.4305	0.0234
4/6	0.3717	0.1937	0.079 <mark>4</mark>	0.0042	16/17	1.4312	0.0223
5/6	0.2748	0.2094	0.2269	0.0329	Total :	20.8718	
6/6	0.0000	0.0000	0.0000	0.0000			
							1
		Output App	oly +/-	<u>A</u> nim <u>O</u> K		Qutput Apply +/-	<u>A</u> nim <u>O</u> K

*Stock:* The Stock page displays the material distribution, after the current operation is completed, in reference to the theoretical profile. This can thus be of great use when :

- roughing a slot, where the amount of material left for finishing is known (left below);
- finishing the fillet with negative Stock such as to produce a protuberance (right below).



**Operations:** The Operations page allows saving combinations of Machine, Tool and Cutting Cycle selections, for the current geometry, under one identifier such as to be able to use the same combinations with different geometries and when defining Processes.

💒 5 Axis C	CnC - Gear 17x67 CycloPalloid.HyG - [mm]
Machine/1	Tool Cutting Cycle Arbor Ball Mill Op/Process Stock
Operati	ion
Name:	FilletFinish/5mm BMill/-1.5mmStock  FilletFinish/5mm BMill/-1.5mmStock   FilletFinish/5mm BMill/-1.5mmStock   FilletFinish/5mm BMill/-1.5mmStock
	Save Delete Import Output FiletRoughing - 40degAngle-12mmx40deg Elank Enish /Endbil/Ostock
	Rank Roughing - 40deg x12mm EndMill
Process	\$
Name:	
	Save Delete Import Output
	Available Operations Process Content
	>>> Up
	Qutput Apply +/- Anim QK Cancel
	Operations Tab

- an Operation is specific to a geometry, i.e. it is saved in the "Operations.fil" file stored in the current geometry's folder;
- the Save / Delete buttons conserve and erase the selected operation;
- the Import button allows importing Operations from other geometries; thus, Operations can be re-used;
- the Output button generates the part program for the selected Operation.

**Operations:** The STEP button displays a selection window where one Flank and one Fillet operation are selected, and then combines the selected operations in one STEP file which can be read by any CAD-CAM software, such that the actual shape of the final tooth can be exported for assessment.



*Output:* The Output button instructs HyGEARS to read the selected user choices, generate the part program and send the output to a Text Results window.

5 Axis CnC - Gear 17x67 Cyclo lachine/Tool Cutting Cycle Arb	Palloid.HyG - [mm] oor Ball Mill Op/Process Sto	uck
Output Format	Stock/Feed Read	Suga, Actual
CSV Format	# Steps 21	[21] Start: 12  Display
CMM Coords/ Normals	# Facewidth Pts 15	End: 21 Display
No comment lines	Retract Factor 4.0	
Coordinates only	Finish Stock -1.500	
Work coordinates	Rough Stock 0.381	
TCPM (Heidenhain)	Constant D-Radius	Moving Contact Pnt
_ , , ,	Clearance	Indexing Sequence
	Tooth Toe 0.0	Skip # 1
	Tooth Heel 0.0	Mirror
Cutting Cycle		
Slot By Slot	IB Side	OB Side
Flank by Flank	Toe -> Heel -> Toe	Toe -> Heel -> Toe
Gliet / Peet	Heel -> Toe -> Heel	Heel -> Toe -> Heel
<ul> <li>Tooth Flank</li> </ul>	Toe -> Heel	Toe -> Heel
Tip Deburring Tool Side	Heel -> Toe	Heel -> Toe
Tip Deburring Tool End	IB-OB O-Shaped	OB-IB O-Shaped
Depth 0.000	Rock Me (babe)	
	Output Apply	

A part program comprises:

- a Header, in which user selections, machine settings and tool definition are listed; this is optional at output time using the "No comment lines" switch;
- a Preamble, specific to the selected machine, where machine code desired by the operator is added automatically;
- the Indexing Sequence, where each tooth slot calls the actual cutting program in the specified sequence order;
- *the actual cutting program with tool path coordinates;*
- Work Coordinates indicate that X, Y and Z are in work piece coordinates, and that angles A, B, C are machine angles;
- Traori, TCPM and TCP indicate that the unit vector of the tool axis is provided along with X, Y and Z in work piece coordinates.

**Output:** the Header lists user selections, machine settings and tool definition.

Codes - Cutting Data Gear [Finishing]	💒 GCodes - Cutting Data Gear [Finishing]	Statute 1	
e <u>E</u> dit	<u>F</u> ile <u>E</u> dit		
EGIN PGM 17x67 CycloPalloid MM	; TopRem Radius :	0.0000 0.0000	1
	; Cutter Gaging :	0.0000 0.0000	Thereas
21 01600-1500 ; Rai (MA			14a
) Q1601-500 ; Filinge Fee			
	: GEAR [FINISHING] :Zvclo-Palloid		
• Date / Time • 06/10/2014 / 6•59•58 IM	: MACHINE SETTINGS - #1757	(T.B.) (0.B.)	
: General Units :: [mm] [dd.mm.ss]	;	(1121) (0121)	
: Cutter Units :: [mm]	·		
: Prepared by :: Claude Gosselin	. V Factor	0,0000	
; Version : 4.0.403.80-456	, A Factor :	214 0215 214 0215	
	; Radiai Distance :	/14.9/15 /14.9/15	
; Start Header	; Cutter lift :	0.0000 0.0000	
; HyGEARS V 4.0 © ®	; Swivel Angle :	0.0000 0.0000	
;	; Blank Offset :	0.0000 0.0000	
; Part Program : 17x67 CycloPalloid.HyG	; Machine Root Angle :	75.7627 75.7627	
;	; Machine Center To Back :	0.0000 0.0000	
; Machine : CnC [Depo-BA Type] - [Finishing][Nominal]	; Sliding Base :	-31.2400 -31.2400	
	; Rate of Roll :	1.03169 1.03169	
; Operation :	; Cradle Angle :	27.5474 27.5474	
2 Number	; Helical Motion [mm]/Rad :	0.00000 0.00000	
; Member : Gear	; 2nd :	0.00000 0.00000	
; Controller : neldennaln	; 3rd :	0.00000 0.00000	
; Coordinates : Machine	; 4th :	0.00000 0.00000	
Stock laft	; 5th :	0.00000 0.00000	
B byis Offset : 0.000	; 6th :	0.00000 0.00000	
: B Axis Length : 0.000	: MRoll 2C :	0.00000 0.00000	
: Tool Length : 0.000	: MBoll 6D :	0.00000 0.00000	
; Apex Location : 0.000	: MBoll 24D	0.00000 0.00000	
; # Steps : 21	: MB011 120F	0.00000 0.00000	
; Start : 10	: MR011 720G	0.00000 0.00000	
; End : 21	, morr , 200	0.00000 0.00000	
; # Points width : 15	. NORVETECE DIMENSIONS		
; Retract factor : 4.0	; WORKFIECE DIMENSIONS		
; Toe Clearance : 0.000	A Tranh	67	
; Heel Clearance : 0.000	; # leeth :	67	
; Compensation : Tool Center Point	, Module :	24.627	
; Cutting Cycle : Slot by Slot	; Face Angle :	75.763	
; latget : Fillet Area	; Face Width :	205.000	
· OB/Bight Cycle · Top-Heel-Top	; Front Grown to Xp :	146.035	
	; OD Toe :	1259.127	
	; OD Heel :	1656.534	
. CPAD (FINICUINC)	; BALL MILL TOOL DEFINITION		
· CLIMTED SPECIFICATIONS (I B) (O B)	;		
	; Name :		
·	; Stem Diameter :	3.000	
; Point Radius : 359.9178 340.1061	; Ball Diameter	5.000	
; Mean Radius : 347.2324 352.7915	; Tool Length	75.000	
; # of Groups/Blade per Group : 3 2			
; Blade Angle : 22.1003 22.1003	,		
; Blade Edge Radius : 4.8000 4.8000	FN 0: 01600=1500		
; Point Width : 5.5000 5.5000	EN 0. 01601-50		
; Rad. of Curvature : 3873.5128 3873.5128	EN 0. 01602-50		
; Rad. of Curvature-Ref. Height : 0.0000 0.0000	LU 0: ÅT005=200		
: TopRem Depth : 0.0000 0.0000	; Start of Program		

*Output: Header* – 1<sup>st</sup> part

*Output: Header*  $-2^{nd}$  *part* 

**Output:** Indexing Sequence: indexes the work piece axis in the specified sequence.

GCodes - Cutting Data Gear (Fir	lisningj	CONTRACTOR OF THE OWNER	
<u>F</u> ile <u>E</u> dit			
;	<ul> <li>Start of Progr</li> </ul>	am	V4
;	- Reference Positio	n	Think
6 L B+0 F200			1440
;	<ul> <li>Start of Cycle</li> </ul>		
;	Tooth Space # 1		
9 L B-5.373135 F200			
10 CALL LBL 1			
;	Tooth Space # 2		
12 L B-10.746270 F200			
13 CALL LBL 1			
;	Tooth Space # 3		
15 L B-16.119405 F200			
16 CALL LBL 1			l
;	Tooth Space # 4		
18 L B-21.492540 F200			
19 CALL LBL 1			
;	Tooth Space # 5		
21 L B-26.865676 F200			
22 CALL LBL 1			
;	Tooth Space # 6		
24 L B-32.238811 F200			
25 CALL LBL 1			
;	Tooth Space # 7		
27 L B-37.611946 F200			
28 CALL LBL 1			
;	Tooth Space # 8		
30 L B-42.985081 F200			
31 CALL LBL 1			
;	Tooth Space # 9		
33 L B-48.358216 F200			
34 CALL LBL 1			
	Tooth Space # 10		
36 T. B-53,731351 F200	10000 ppace # 10		
37 CALL LBL 1			
•	Tooth Space # 11		
39 T. B-59 104486 F200	10000 Space # 11		
40 CALL IBL 1			
10 CADD DDD 1	Tooth Space # 12		
2 T R_64 477621 F200	rooth space # 12		
42 CAIT IDT 1			
TO CALL LDL I	Tooth Spage # 10		
;	rooth space # 13		
45 L D-69.850756 F200			
40 CALL LEL 1	Treeb Correct 5 44		
;	looth Space # 14		
48 L B-75.223891 F200			
49 CALL LBL 1			
;	Tooth Space # 15		
51 L B-80.597027 F200			
52 CALL LBL 1			
;	Tooth Space # 16		
54 L B-85.970162 F200			
55 CALL LBL 1			

*Output: Header – Indexing Sequence* 

*Output:* Tool path coordinates: the actual tooth flank cutting commands.

🥁 GCodes - Cutting Data Gear [Finishing]		
<u>File</u> <u>E</u> dit		
209 M30		V4
; Cutting Cycle		Thinks
211 LBL 1		144
; Section 1		
; Convex		
; Toe		
217 FQ1600 210 J MAD FCTDC M14D DDDCT 7 CCD FCCDF C C FDFTDD D 75 D71045	;	Rapid Move P
218 L X42.56/36 1142.2306/ 2-665.56635 C-6.535/98 A-/5.3/1945		; Retracte
210 FW1001 210 F ¥23 07060 V_27 86558 7_618 88010 C_6 535708 8_75 371045	'	· Poll·
219 E A23.07903 1-27.00330 2-010.00019 C-0.000790 A-70.071910		Cutting Feer
221 T. X21 04126 Y-31 48729 7-633 17021 C-6 419333 A-75 174878		· Roll· ·
222 L X18.34335 Y-35.10868 Z-647.46879 C-6.283244 A-74.977407		: Roll: -
223 L X14.97476 Y-38.73004 Z-661.76749 C-6.128104 A-74.782069		: Roll: -
224 L X10.92143 Y-42.35052 Z-676.05669 C-5.954526 A-74.587002		; Roll: -
225 L X6.16927 Y-45.97526 Z-690.32367 C-5.756723 A-74.387983		; Roll: -1
226 L X0.69642 Y-49.59620 Z-704.55785 C-5.543614 A-74.193049		; Roll: -(
227 L X-5.51718 Y-53.21638 Z-718.74372 C-5.311808 A-74.000103		; Roll: -
228 L X-12.49535 Y-56.83656 Z-732.86466 C-5.060467 A-73.809651		; Roll:
229 L X-20.26578 Y-60.45567 Z-746.90244 C-4.790207 A-73.622287		; Roll:
230 L X-28.85886 Y-64.07475 Z-760.83597 C-4.499735 A-73.438604		; Roll:
231 L X-38.30932 Y-67.69387 Z-774.64176 C-4.188474 A-73.259280		; Roll:
232 L X-48.65679 Y-71.31249 Z-788.29339 C-3.856241 A-73.085049		; Roll:
233 L X-59.94596 Y-74.93091 Z-801.76056 C-3.501996 A-72.916725		; Roll:
234 L X-72.22834 Y-78.54833 Z-815.00888 C-3.128365 A-72.758208		; Roll:
; Heel		
236 L X-71.97428 Y-78.67041 Z-814.97118 C-2.740001 A-73.082369		; Roll:
237 L X-59.70047 Y-75.05474 Z-801.71963 C-3.097793 A-73.224629		; Roll:
238 L X-48.41908 Y-71.43810 Z-788.24975 C-3.435655 A-73.374349		; ROII:
239 L X-38.0/864 Y-6/.82130 Z-7/4.59585 C-3.752653 A-73.529501		; ROII:
240 L X-28.63434 I-64.20402 2-760.78815 C-4.049821 A-73.689303		; ROII:
241 L X-20.04/20 1-60.50604 2-740.05305 C-4.52/265 A-73.053055		; ROII:
242 L X-12.20109 1-50.909/1 2-732.01100 C-1.303329 X-74.020100		, ROII.
244 T YO 90114 Y-40 73331 7-704 50548 C-5 047036 3-74 361846		· Poll: -
245 T. X6 37037 Y-46 11437 7-690 27082 C-5 252248 3-74 535486		· Roll· -
246 J. X11.12099 Y-42.49565 Z-676.00243 C-5.438163 A-74.710290		: Roll: -
247 L X15.17143 Y-38.87665 Z-661.71326 C-5.606764 A-74.888663		: Roll: -
248 L X18.53765 Y-35.25707 Z-647.41491 C-5.755847 A-75.059682		; Roll: -
249 L X21.23370 Y-31.63754 Z-633.11673 C-5.887716 A-75.237363		; Roll: -
250 L X23.27076 Y-28.01777 Z-618.82735 C-6.000320 A-75.410304		; Roll: -
; Toe		
252 L X23.47193 Y-28.16972 Z-618.77402 C-5.455723 A-75.451087		; Roll: -
253 L X21.43611 Y-31.78729 Z-633.06283 C-5.346966 A-75.298374		; Roll: -
254 L X18.74179 Y-35.40466 Z-647.36066 C-5.220032 A-75.142409		; Roll: -
255 L X15.37780 Y-39.02212 Z-661.65887 C-5.076882 A-74.993182		; Roll: -
256 L X11.33004 Y-42.63899 Z-675.94810 C-4.915538 A-74.837509		; Roll: -
257 L X6.58258 Y-46.25561 Z-690.21680 C-4.737696 A-74.684311		; Roll: -:
258 L X1.11704 Y-49.87253 Z-704.45198 C-4.542394 A-74.532000		; Roll: -(
259 L X-5.08829 Y-53.48867 Z-718.63937 C-4.330542 A-74.381080		; Roll: -
260 L X-12.05712 Y-57.10494 Z-732.76234 C-4.101154 A-74.232003		; Roll:
201 L X-19.01/20 Y-60.72007 Z-746.80274 C-3.855106 A-74.085312		; KOI1:

*Output: Tool path coordinates (with comments)* 

Sample Results:

13x37 6.5 mm module, hypoid gear set: **soft-finish**. Contact Pattern checks show perfect agreement with HyGEARS' prediction.



Sample Results:

13x37 6.5 mm module, hypoid gear set: **hard-finish**. Contact Pattern check shows perfect agreement with HyGEARS' prediction.



13x37 hypoid gear pair on the VH tester

- *Pinion Fixed Setting Generated*
- Gear Spread Blade Generated
- *Cut on DMU65 Monoblock (AC type machine)*
- Roughing : CoSIMT
- Pre-Finishing : Bull Nose End Mill
  - Hard finish : Tapered End Mill

Actual Contact Pattern Pinion OB



HyGEARS' Predicted Contact Pattern Pinion OB



Sample Results: 13x37 6.5 mm module, hypoid gear set: Pinion CMM output after hard-finish shows negligible deviations between actual and HyGEARS' theoretical.



Sample Results: 13x37 6.5 mm module, hypoid gear set: Gear CMM output after hard-finish shows negligible deviations between actual and HyGEARS' theoretical.



## <u>Summary</u>

- 1. HyGEARS' tooth flank generation and TCA calculations match Gleason's CAGE and Klingelnberg's KIMoS; therefore, the **reference topography** in HyGEARS is the **exact tooth** *definition*;
- 2. *HyGEARS designs gear set geometries*, i.e. the machine settings for all HyGEARS supported geometries are calculated and a Summary is created;
- 3. Geometries can be imported from Gleason SPA and KIMoS ND files;
- 4. Spiral bevel cutting processes such as Face Milling and Face Hobbing are integral to HyGEARS;
- 5. Geometries can be analyzed unloaded and loaded for contact and tooth fillet stresses;
- 6. **5Axis CnC machine Post-Processing**, i.e. the generation of a part program "machine ready", is integral to HyGEARS;
- 7. Part programs are **generated in reference to the exact tooth surface** definition (rather than an interpolated surface as is the case with the many other softwares);
- 8. Part program generation is based on user selected cycle features;
- 9. Any 5Axis CnC machine architecture can be accommodated; current architectures include "AB", "AC", "BA" and "BC"; any controller can be accommodated; current controllers include GCodes, Siemens, Heidenhain and Fanuc;
- 10. Part programs can be in Machine coordinates, Work piece coordinates with axis angles, or Work piece coordinates with tool axis vector (Traori, TCPM and TCP);

## <u>Summary</u>

- 11. Users can define their own tool box for Face Mill, CoSIMT, End Mill and Ball Mill tools;
- 12. Cutting Cycles include **Slot by Slot** and **Flank by Flank**, both for tooth flank and fillet; tip chamfering is available;
- 13. Animations and single stepping allow the visualization of tool movements and the verification of tool paths and possible interference;
- 14. A "Metrics" function gives an estimate of the deviations between the theoretical tooth flank and the "flats" and "peaks" created by the discrete movements of the tool;
- 15. Toe and Heel clearances allow smooth tool entry and exit;
- 16. "Stock" allowance is available for roughing and finishing;
- 17. A **"Roughing mode"** moves the selected tool in the center of the gap to quickly remove as much material as possible;
- 18. "Operations", including all user selections for a given task, may be saved for later re-use;
- 19. *Closed Loop*, also called Corrective Machine Settings, is *integral to HyGEARS* and allows the seamless manufacture of gears to the required tolerances.

#### HyGEARS covers every need for the design and manufacture of gears.